# **Systems Dynamics**

Course ID: 267MI - Fall 2018

Thomas Parisini Gianfranco Fenu

University of Trieste Department of Engineering and Architecture



# **Course administration**

#### **Lecturers & examiners**

- Thomas Parisini (t.parisini@gmail.com)
- Gianfranco Fenu (fenu@units.it)

### Course home page

- slides, exercises and computer code examples
- old exams

## http://control.units.it

#### **Course credits**

• 9 CFU



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# **Course Overview**

# Examination

- **Final exam**: a preliminary written examination followed by oral questions.
- The **final grade** depends on both the written part and the outcome of the oral discussion.
- Written examination and oral discussion usually usually take during the same exam session.

## Examination (cont.)

#### Written examination

The exam paper consists of 3 – 4 essay questions:

- typical numerical application problems
- specific questions about theoretical aspects (theorems, properties, definitions) could be included

#### **Oral questions**

Oral questions deal with any possible topic, discussed and analysed in the lectures.

 A short discussion about the written examination results generally also takes place

## Examination (cont.)

#### Homework (not compulsory)

- Advanced engineering specific projects are offered during the course, characterised by challenges more difficult to address than the usual ones.
- The aim is to stimulate learning advanced concepts during the course also to help the learning exercise
- These projects are then evaluated upon request by the students.
- It's allowed to solve the projects in groups, up to 3 persons.
- Working on homework problems is not compulsory

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TP GF – L0–p3

## Examination (cont.)

#### Homework & final grade

- Homework contributes to the final grade, with an increment of the score up to 2 points.
- The grading of the homework is **independent** from the grading of the examination

# Exam sessions

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#### Examination timetable

- 3 sessions in January–February
- 3 sessions in June–July
- 1 session in September

## How to sign up for examinations

- In order to participate to the exam session you must sign up/register for the exam (compulsory)
- To sign up, use the students university career management system Esse3 to access to the on-line University Services.
- Please, pay attention to the dates of the registration periods and the examination periods!

TP GF - L0-p4

## **Course Information**

#### Prerequisites

#### **Course organization**

- Linear algebra, calculus and complex analysis
- Course 034IN "Fundamentals of automatic control" (or equivalent for students enrolled from other universities/programs)
- Basic knowledge of probability and statistics is not mandatory, but highly helpful

LecturesExercise sessions

## Desiderata

## Students who pass the course should be able to:

- carry out a complete and comprehensive analysis of the main properties of deterministic and stochastic discrete-time dynamic systems;
- design and implement parametric estimation and identification, and state estimation algorithms that use available data or data collected in real-time with reference to engineering application scenarios;

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# Desiderata (cont.)

## Students who pass the course should be able to

- evaluate, among several options, what's the best choice of parametric estimation and identification, and state estimation algorithms starting from requirements and considering technological constraints;
- describe in a clear and plain way the functionalities of a parametric estimation and identification, and state estimation algorithm in the context of discrete-time dynamic systems and with the correct use of technical terminology

# Lecture Plan

#### Lect. Content

- 1 Course overview. Generalities: systems and models (defs, props, problems).
- 2 Sampling and discrete-time representation of continuoustime dynamic systems.
- 3 Time-evolution of state and output of linear dynamic systems.
- 4 Stability of discrete-time dynamic systems.
- 5 Model identification from data.
- 6 A glimpse on prob. theory, random vars and discrete-time stochastic processes.

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## Lecture Plan (cont.)

#### Lect. Content

- 7 Definitions and properties of the estimation and prediction problems.
- 8 Dynamic models of stationary discrete-time stochastic processes.
- 9 Least-squares estimation.
- 10 Bayes estimation.
- 11 Solution of the prediction problem.
- 12 Identification of discrete-time stochastic models from observed data.
- 13 State estimation from observed data.

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## References

References on dynamic systems analysis:

P. J. Antsaklis and A. N. Michel. *Linear Systems.* Birkhäuser, 2006.

G. Calafiore. *Elementi di Automatica.* CLUT, Torino, 2007. (in Italian). G. Marro. **Teoria dei Sistemi e del Controllo.** Zanichelli, 1989. (in Italian).

S. Rinaldi. **Teoria dei Sistemi.** CLUP, Milano, 1977. (in Italian).

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# **References (cont.)**

References on data-based estimation and identification:

T. Söderström. P. Stoica. *System Identification.* Prentice Hall, 1989.

L. Ljung. **System Identification – Theory for the User.** Prentice Hall, 1999.

S. Bittanti. **Teoria della predizione e del filtraggio.** Pitagora Editrice, Bologna, 2000. (in Italian). S. Bittanti.

Identificazione dei Modelli e Controllo Adattativo. Pitagora Editrice, Bologna, 1997. (in Italian).

S. Bittanti, M. Campi. Raccolta di Problemi di Identificazione, Filtraggio, Controllo Predittivo. Pitagora Editrice, Bologna, 1996. (in Italian).

