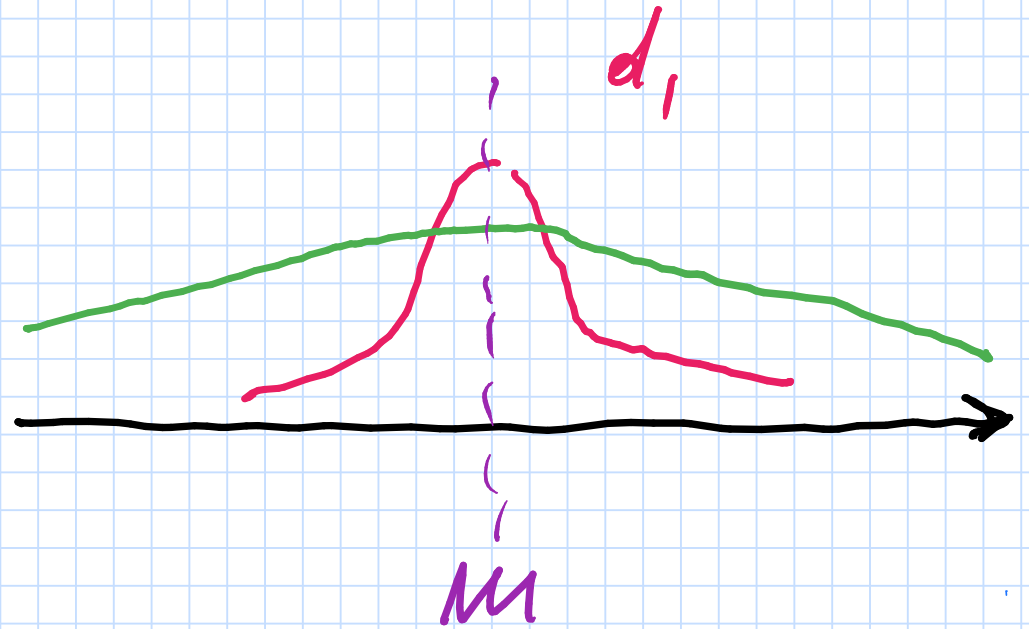


Es 2 v. a. indipendenti, gaussiane d_1, d_2

$$d_1 \sim \mathcal{G}(m, 2)$$

$$d_2 \sim \mathcal{G}(m, 4)$$



Stimare m con una osservazione di d_1 ed d_2

$$\hat{m} = \alpha d_1 + \beta d_2$$

① NO BIAS

$$E(\hat{\mu}) = \mu$$

$$E[\hat{\mu}] = \alpha E[d_1] + \beta E[d_2]$$
$$= (\alpha + \beta) \mu$$

$$\text{NO BIAS} \iff \alpha + \beta = 1$$

② variance minimale

$$\text{var } \hat{u} = E[(\hat{u} - u)^2]$$

$$\hat{u} = \alpha d_1 + \beta d_2$$

$$\alpha + \beta = 1$$

$$= E[(\alpha d_1 + \beta d_2 - \underbrace{1}_{\alpha + \beta} \cdot u)^2]$$

$$= E[(\alpha(d_1 - u) + \beta(d_2 - u))^2] \rightarrow$$

$$\rightarrow \alpha^2 E[(d_1 - \mu)^2] + \beta^2 E[(d_2 - \mu)^2]$$

$\rightarrow$ tutti gli altri termini valgono 0

$$= \alpha^2 \cdot 2 + \beta^2 \cdot 4 = 2\alpha^2 + 4\beta^2$$

$$\alpha + \beta = 1 \rightarrow \beta = 1 - \alpha$$

$$\text{var } \hat{\mu} = 6\alpha^2 - 8\alpha + 4$$

$$\text{var } \hat{u} = 6\alpha^2 - 8\alpha + 4$$

$$\frac{d}{d\alpha}(\text{var } \hat{u}) = 0 \rightarrow 12\alpha - 8 = 0$$

$$\begin{cases} \alpha = \frac{2}{3} \\ \beta = \frac{1}{3} \end{cases}$$

$$\hat{u} = \frac{2}{3}d_1 + \frac{1}{3}d_2$$

$$\text{var } \hat{u} = \frac{4}{3}$$

[45] (a) consideriamo 2 v. r. x, w

$$E(x) = 0$$

$$E(w) = 0$$

scorrelate

$$\sigma_x^2 = 1$$

$$\sigma_w^2 = 1$$

$$E(xw) = 0$$

Vuoi conoscere il valore attuale di x all'istante t (faccio un esperimento) $\rightarrow x$ non realizzabile. Posso osservare un'altra v. r.

$$y = x + w$$

$$\hat{x} = ?$$

stimulator linear output

$$\hat{y} = \frac{d_{yd}}{d_{dd}}$$

Δ_{yd} Δ_{dd}^2 d (circled) $\downarrow$ observation time

$$\begin{matrix} d \leftrightarrow y \\ y \leftrightarrow x \end{matrix}$$

$$\begin{matrix} d_{dd} \leftrightarrow \Delta_{yy}^2 \\ d_{yd} \leftrightarrow \Delta_{xy} \end{matrix} \quad \parallel$$

$$E(y) = ?$$

$$y = x + w$$

$$\rightarrow E(y) = E(x) + E(w)$$

$$= 0$$

$$\nabla_y^2 = \nabla_x^2 + \nabla_w^2 = 2$$

$\nwarrow \nabla_{xw} = 0$

$$\sigma_d = \nabla_{xy} = E(xy) \quad y = x + w$$

$$E(xy) = E[x(x+w)] = \rightarrow$$

$$E(xy) = E[x(x+w)] = \underbrace{E(x^2)}_{\sigma_x^2} + \underbrace{E(xw)}_0$$

$$= 1 = \sigma_{xy}$$

$$\hat{x} = \frac{\sigma_{xy}}{\sigma_{yy}} \cdot y = \frac{1}{2} y$$

$$\text{var}(\theta - \hat{\theta}) = \sigma_{\theta\theta} - \frac{\sigma_{\theta d}^2}{\sigma_{dd}}$$

Supponiamo che le v.r. sono x, w, z IND.
e di poter fare 2 osservazioni differenti

$$x \rightarrow E(x) = 0$$

$$\Delta_x^2 = 1$$

$$w \rightarrow E(w) = 0$$

$$\Delta_w^2 = 1$$

$$z \rightarrow E(z) = 0$$

$$\Delta_z^2 = 2^2$$

$$\begin{cases} y_1 = x + w \\ y_2 = x + z \end{cases}$$

$$\hat{g} = \underbrace{\Lambda}_{g_d} \cdot \underbrace{\Lambda^{-1}}_{d d} \cdot d$$

$$\hat{x} = \underbrace{\Lambda}_{x_d} \cdot \underbrace{\Lambda^{-1}}_{d d} \begin{bmatrix} g_1 \\ g_2 \end{bmatrix}$$

$$\underbrace{\Lambda}_{d d} = \begin{bmatrix} \sigma_{g_1}^2 & \sigma_{g_1 g_2} \\ \sigma_{g_2 g_1} & \sigma_{g_2}^2 \end{bmatrix}$$

$$\sigma_{g_1}^2 = 2$$

$$\sigma_{g_2}^2 = 1 + d^2$$

$$\Sigma_{y_1 y_2} = E[y_1 y_2] = E[(x+w)(x+z)]$$

$$= E(x^2) + \cancel{E(xw)}_0 + \cancel{E(xz)}_0 + \cancel{E(wz)}_0$$

$$= 1$$

$$\Lambda_{old} = \begin{bmatrix} 2 & 1 \\ 1 & 1+\sigma^2 \end{bmatrix}$$

$$\Lambda_{dd}^{-1} = \begin{bmatrix} \frac{d^2+1}{2d^2+1} & -\frac{1}{2d^2+1} \\ -\frac{1}{2d^2+1} & \frac{2}{2d^2+1} \end{bmatrix}$$

$$\Lambda_{d\sigma} = \begin{bmatrix} F(y_1 x) \\ F(y_2 x) \end{bmatrix} \quad \Lambda_{\sigma d} = \Lambda_{d\sigma}^T$$

$$E(g_1 x) = E[(x+w)x] = 1$$

$$E(g_2 x) = E[(x+z)x] = 1$$

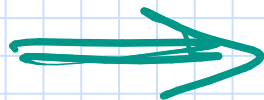
$$\Lambda_{d0} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Lambda_{d1} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\hat{x} = \frac{1}{\sigma_d} \cdot \frac{1}{d} \cdot d = \frac{1}{d} \cdot \frac{1}{d} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$= \frac{1}{2d^2 + 1} (y_2 + d^2 y_1)$$

$$\text{se } d^2 \gg 1$$



$$\hat{x} \rightarrow \frac{1}{2} y_1$$

$$\text{se } d^2 \ll 1$$



$$\hat{x} \rightarrow y_2$$

$$\begin{cases} x \\ y \end{cases} \quad y_2 = z \quad ?$$

$$\begin{cases} y_1 = x + w \\ y_2 = z \end{cases}$$

$$E(z) = 0$$

$$V_z^2 = 1$$

$$E(xw) = 0$$

$$E(xz) = 0$$

$$E(wz) = 0$$

$$\Lambda_{dd} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\Lambda_{\sigma\sigma} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\hat{x} = \Lambda_{\sigma d}^{-1} \Lambda_{\sigma d}^{-1} d$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$= \begin{bmatrix} 1/2 & y_1 \end{bmatrix}$$

$$\text{var}(x - \hat{x}) = \sigma_x^2 - \underbrace{1}_{\sigma_d} \underbrace{K^{-1}}_{dd} \underbrace{1}_{d\sigma}$$

$$= I - \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= 1/2$$

Eg Processo stocastico descritto da

$$\begin{cases} y(t) = a^0 u(t) + v(t) \\ v(t) = e(t) + \frac{1}{2} e(t-1) \end{cases}$$

$$e \sim WN(0, 1)$$

$$u(t) \equiv 1 \quad \forall t \quad (\text{deterministico})$$

$$M \quad y(t) = a u(t) + \eta(t) \quad \eta \sim WN(0, \sigma^2)$$

Si vuole stimare e usare MEP LS.

$$\hat{a}(N) \xrightarrow{N \rightarrow +\infty} ?$$

$$\text{MEP} \rightarrow \hat{y}(t|t-1) = ?$$

$$y(t) = a u(t) + \cancel{y(t)}$$

predittore
ad 1 passo

$$\hat{y}(t|t-1) = a u(t)$$

errore di predizione

$$\varepsilon(t) = y(t) - \hat{y}(t|t-1)$$

funzionale di costo

$$J_N(\alpha) = \frac{1}{N} \sum_{t=1}^N \varepsilon^2(t)$$

per $N \rightarrow \infty$

$$J_N(\alpha) \xrightarrow{N \rightarrow \infty} E[\varepsilon^2(t)]$$

$\parallel = J(\alpha)$

$$J(a) = E[\varepsilon^2(t)] = ?$$

$$\varepsilon(t) = y(t) - \hat{y}(t|t-1) \quad \hat{y}(t|t-1)$$

$$= \underbrace{a^0 u(t) + v(t)}_{y(t)} - \overbrace{a u(t)}$$

$$= (a^0 - a) u(t) + v(t)$$

$$\varepsilon(t) = (a^0 - a) + v(t)$$

$$J(a) = E[\varepsilon^2(t)] =$$

$$= E[(a^0 - a) + v(t)]^2 =$$

$$= (a^0 - a)^2 + E[v^2(t)] + 2(a^0 - a)E[v(t)]$$

→ ~~⊗~~

$$E[v^2(t)] =$$

$$v(t) = e(t) + \frac{1}{2}e(t-1)$$

$$e \sim \mathcal{N}(0, 1)$$

$$E(v) = 0$$

$\mu_A(1)$

↓

$$\text{var } v = \left[1^2 + \left(\frac{1}{2} \right)^2 \right] \cdot 1$$

$$= \frac{5}{4}$$

$$\begin{aligned}
 \bar{J}(a) &= (a^0 - a)^2 + \overbrace{\mathbb{E}[v^2]}^{5/4} + \\
 &\quad + 2(a^0 - a) \underbrace{\mathbb{E}(v)}_0 \\
 &= (a^0 - a)^2 + \frac{5}{4}
 \end{aligned}$$

$$\min \bar{J}(a) \rightarrow \hat{a} = a^0$$

NB l'errore di predizione è MA(1)